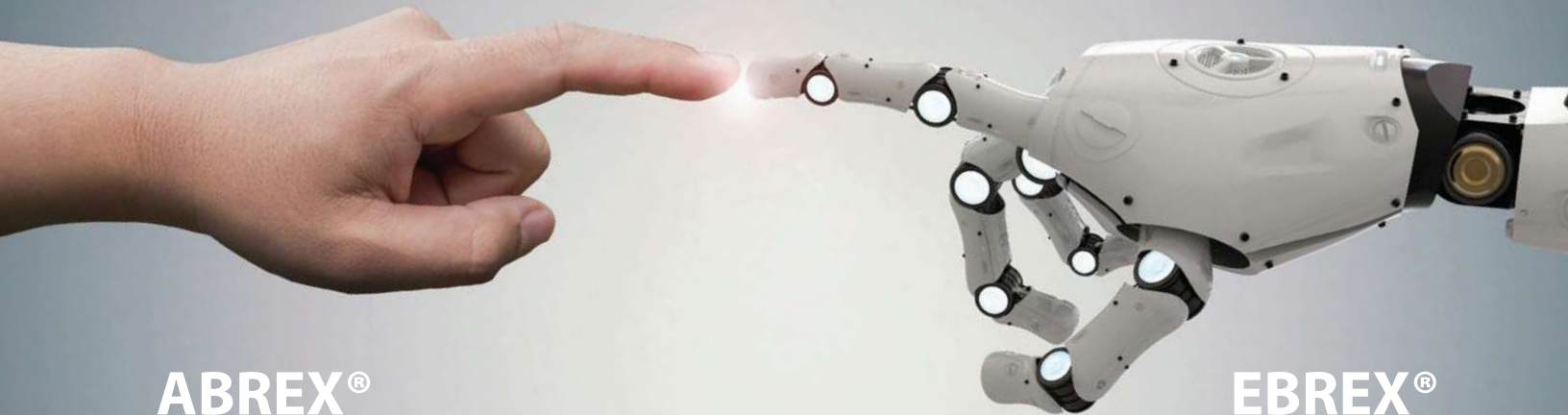
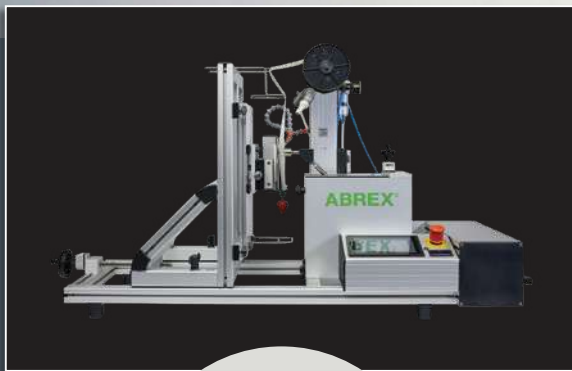


HUMAN TOUCH VS. ROBOT TOUCH



ABREX®



Human Fingertip Touch Simulation
with Pneumatic Drive System

Provide dynamic, non-linear movement

99% simulation providing the same
wear pattern as the one from the field

Feasible air-blow function to avoid
unnecessary abrasive

EBREX®



Robot Finger Touch Simulation with
non-Pneumatic Drive System

Provide linear and constant speed

Perform tribological material testing

Provide high speed performance

No air supply required



INNOWEP®

quality + durability + haptic

Innowep GmbH
+49 (0)931 32298 - 0
Friedrich-Bergius-Ring 11
97076 | Würzburg | Germany
info@innowep.com
www.innowep.com